

# navXperience

## next generation GNSS receivers OSR series



mobile | reference | control Innovative Engineering - Made in Germany

## Ouer precise GNSS receivers **OSR** series

#### **OSR** mobil



Our new development OSR mobile is a so-called Smart antenna with a completely new concept. The inductive rapid charging of the batteries, the robust workmanship and the absolutely low power consumption stand for this new technology - Made in Germany.

Even under the most difficult conditions, we have battery life of more than 8 hours. Our intelligent management ensures careful use of the valuable battery resource and thus a long service life.

With a smartphone you have full access to all functions of the OSR mobile at all times, with fast and modern WLAN and Bluetooth you have wireless communication options.

The OSR mobile can be used as a reference station and also as a rover. All standard interfaces are available (e.g. NTRP, RTCM, RINEX). Of course we work with multi-frequency data from Galileo, GPS, GLONASS and Beidou. The use of the OSR mobile in the moving baseline procedure is also possible.



#### **OSR** reference

Our OSR (open source receiver) is the fi rst programmable reference station receiver in the world and designed for your CORS network with all important features, like a web interface, Linux or Window OS, streaming data and lots of memory (64GB per receiver). The OSR reference has optimal power flexibility for external power input as well as internal battery backup. In a reference receiver configuration, the OSR-Receiver delivers up to fourteen hours operation from the internal battery.

The OSR reference is compatible with every CORS software in the world. Designed to meet the future.

make the OSR reference receivers unique.





Our OSR reference receives the GNSS signals from Galileo, GPS, GLONASS and Galileo. The robust design, the low power consumption and the unique possibility of optional expansion with external instruments (e.g. weather stations)

#### **OSR** contol



The OSR control is our versatile receiver. It is designed for use as a mobile receiver in machine control applications in the construction industry and in agriculture. The OSR control is used to monitor buildings and can be used for deformation analysis of dams. The built-in IMU allows additional applications and makes the OSR control a powerful GNSS receiver.

The OSR control can be equipped with internal batteries with a battery life of up to 20 hours.

Signals from all satellite navigation systems (Galileo, GPS, GLONASS and Beidou) are received and processed. Our robust housing allows use in extreme environments with high acceleration, strong vibrations and high exposure to environmental influences.



#### **OSR twin control**

Our OSR twin control is the extension to receive two GNSS positions simultaneously. He can as s.g. Heading receivers can be used, as well as receivers with two independent positions. Of course, an IMU is also installed here, which is freely configurable and its data is freely accessible to every user, as with all receivers in the OSR series. The OSR twin control can optionally be expanded with batteries and a radio modem. This means that it can be flexibly configured for all areas of application.

The OSR twin control also receives and processes the signals from all satellite navigation systems (Galileo, GPS, GLONASS and Beidou). The same housing concept is used here as with the OSR control, which is suitable for all environmental conditions.

Optionally, an extension to three antenna connections is possible.





### **Technical Data**

## Web interface - functions and protocols

		Our OSR (open source receiver) series are equipped with a LINUX op will be activated free of charge on request. After switching on agair These protocols are available by default: NTRIP, NMEA, RTCM 3.3, over TCPIP ports.	
GNSS Parameter	GLONASS L10F L20F Beidou B1I B2I Galileo E1B/C E5B		
RTK configuration	20 Hz		
Cold start ???	20 sec	<b>PVT:</b> General displays like time, RTK mode, PDOP, Out-	Raw I
Warm start ???	2 sec	put Interval (1 to 20 Hz), Position in ECEF, Lat, Lon, ETRS89 speed and received satellites.	<b>RTK (</b> coord
RTK accuracy	<1cm	<b>Geoid:</b> A geoid model can be stored here.	accura
Postprocessing	< 2 mm	<b>NTrip:</b> An NTRIP client can be configured here.	Log N
Time pulse	0,25 Hz bis 10 MHz	IMU:IMU configuration and calibration.Measure-ment of acceleration, angular velocities, temperature,I6 axis sensors.Accuracy 0.004° per sec and ResolutionI	<b>nfo:</b> ! Entrie
Hardware	Integrated IMU free configurable	0.00006g.	Explo
SD card	32 GB	Satellites: Information about the receiving satellites such as azimuth, elevation, signal strength and status.	<b>Conne</b> well a
GSM modul	LTE	Satellites History: Number of satellites connected to time interval.	Maint
USV	6 h, optional 12 h	<b>Skyplot:</b> Visual representation of the satellites.	poard
TNC	female antenna connector (back)	<b>Survey:</b> Simple recording of measuring points.	apac der, sj
Voltage	9 up to 30 volt	<b>OSRP Data Record:</b> Recording of raw and measure-	date a
Ports	USB C RS 232 serial ethernet port	<b>RINEX Data Record:</b> Configuration of the recording of 2 different data rates. It will zip and Hatanaka compression with RINEX 2 and 3 support.	
Consumption	< 3,5 watt (including antennas)		

Operating temperatur

-45° up to 85° C

operating system. Access to that Operating system gain, the receiver also starts the last configuration.

3.3, RINEX and OSRP raw data as Data logging and

#### w Data Record: Raw data recording.

**K Config:** Including configuration of base or rover, ordinate system, elevation mask, signal level and curacy.

**g Messages:** Setting of 24 parameters and Error essages included in a daily log to be written.

**io:** System information such as the last log file that tries, last boot and firmware version.

plorer: interface for copying and deleting Data.

**nnetions:** Display and configuration of the ports, as II as the settings for FTP and SFTP.

**intenance:** System information on processor permance, Memory usage, processor temperature and ard, uninterruptible power supply status, Battery pacity, setting of maximum sizes the recording folr, specifying the Users and passwords, firmware upte and restart the system.



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